

# Introduction: Formalisms for system design



## ⌘ Object-oriented design.

- ☑ Design is composed of interacting objects
- ☑ Objects: S/W or H/W

## ⌘ Unified Modeling Language (UML).

- ☑ Visual language to conceptualize design

# System modeling/design

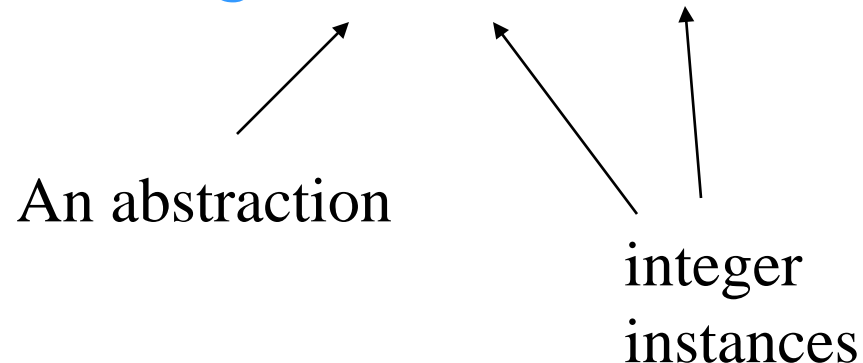


- ⌘ Need languages to describe systems:
  - ☑ useful across several levels of abstraction;
  - ☑ understandable within and between organizations.
- ⌘ Block diagrams are a start, but don't cover everything.

# Object-oriented design

⌘ Object-oriented (OO) design/programming: Design using objects/programming using C++, Java, C, ...

⌘ Class and object: e.g., `int a, b, c;`



# Classes and objects



⌘ **Class: Abstraction of the common properties from a set of objects, e.g., AUTOMOBILE, ROBOT, ...**

⌘ **Object = state + methods.**

☑ **State provides each object with its own identity.**

☑ **Methods provide an **abstract interface** to the object.**

# OO implementation in C++

```
class display {
    pixeltype pixels[IMAX,JMAX];
public:
    display() { }
    pixeltype pixel(int i, int j) {
        return pixels[i,j]; }
    void set_pixel(pixeltype val, int i,
        int j) { pixels[i,j] = val; }
}
display D1; --- D1.pixel(0,0);
```

# OO implementation in C



```
typedef unsigned char pixeltype;
```

```
typedef struct { pixeltype  
    pixels[IMAX,JMAX]; } display;
```

```
display d1;
```

```
pixeltype pixelval(display *px, int i, int  
    j) {  
    return px->pixels[i,j];  
}
```

```
void set_pixel(display *px, pixeltype val,  
    int i, int j){ px->pixels[i,j] = val;}
```

# Recap: Objects and classes



⌘ **Class**: object type → Mechanism to create objects

⌘ **Data**: Class defines the object's state elements but state values may change over time.

⌘ **Function**: Class defines the methods used to interact with all objects of that type.

☑ Each object has its own state.

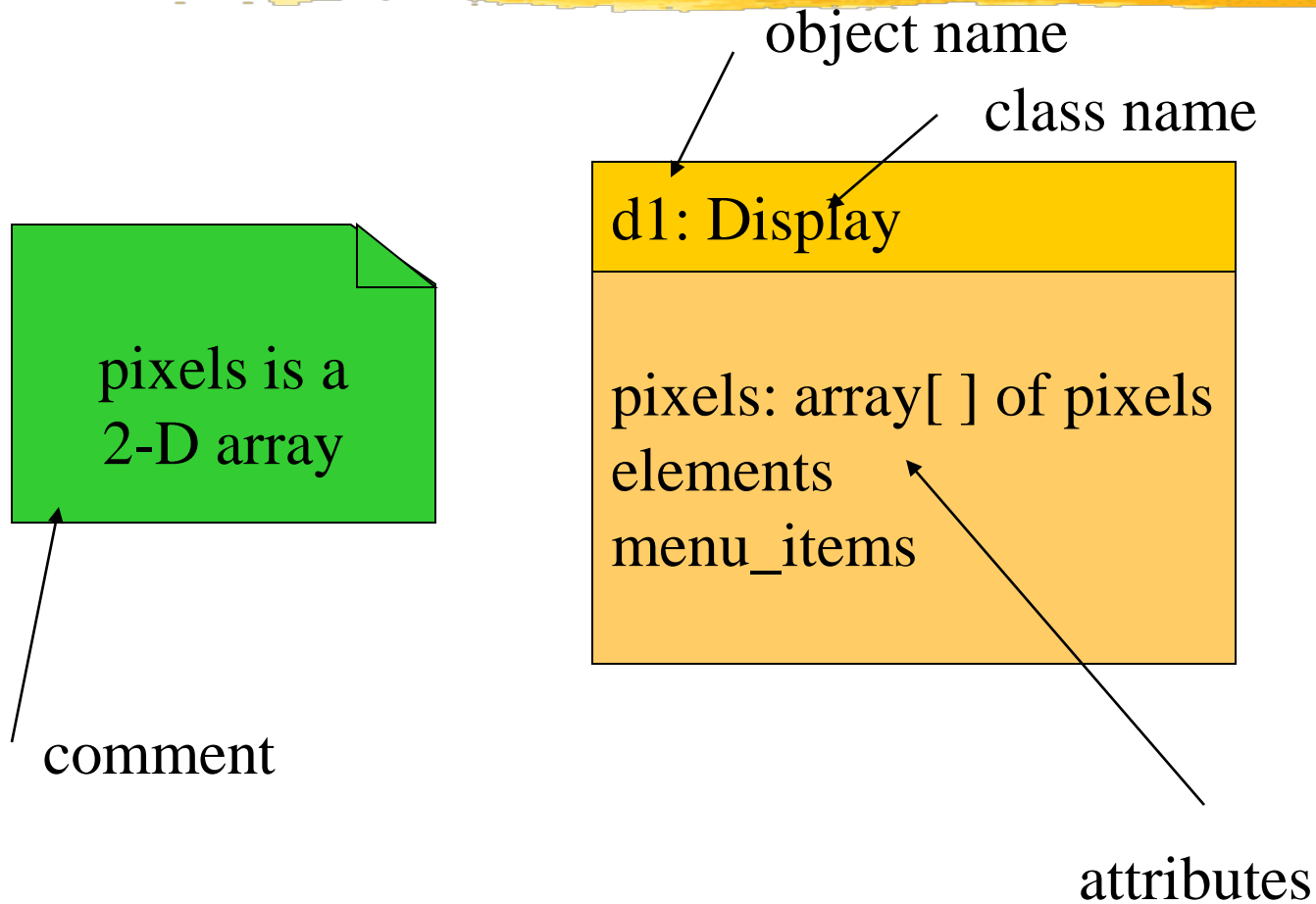
# UML: Visual modeling language

⌘ Developed by Grady Booch et al.

⌘ Goals:

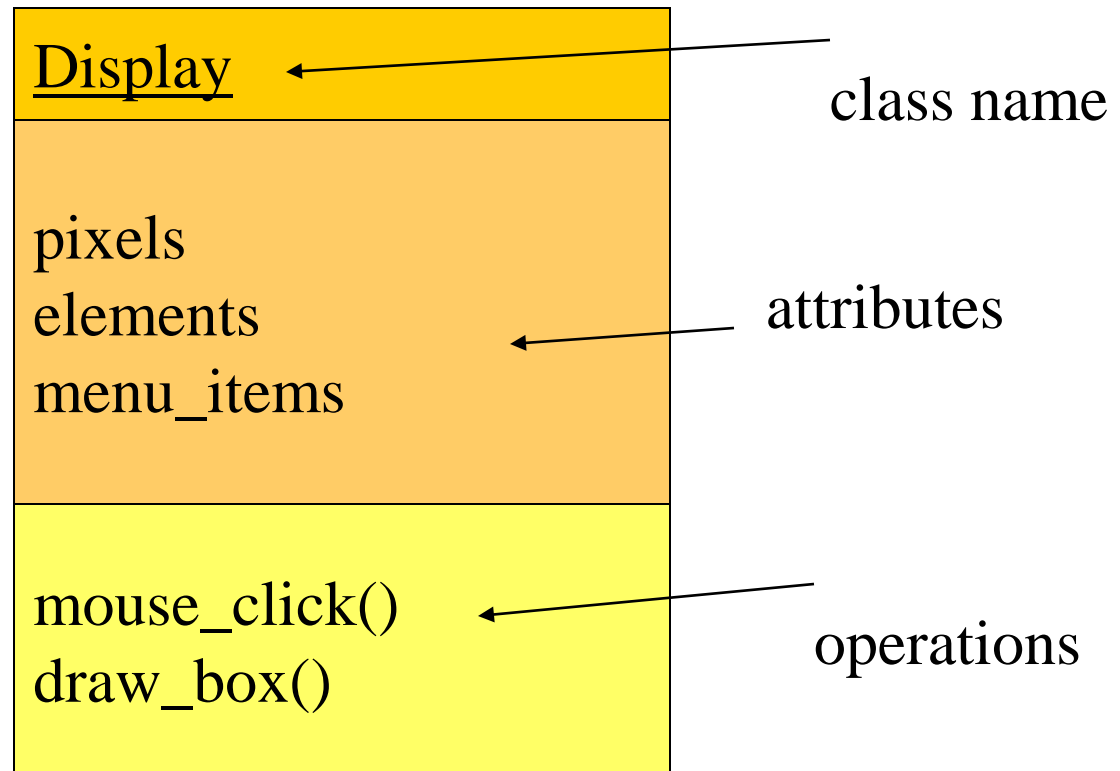
- ☑ object-oriented framework
- ☑ visual
- ☑ usable for modeling complex systems
- ☑ Behavioral modeling with statecharts
- ☑ Support for multi-tasking representation

# UML object



Taken/modified from "Computers  
as Components, W. Wolf"

# UML class



Taken/modified from "Computers  
as Components, W. Wolf"

# The class interface:

State + Operation



- ⌘ Operations (**functions**): Provide the abstract interface between the class implementation and other classes.
- ⌘ Operations: May have arguments, return values.
- ⌘ An operation can examine and/or modify the object's state.

# Choose your objects properly: Good cohesion



⌘ e.g., robot object: joint angles, gripper distance, motion commands

⌘ Reusability: robot object, pid object, ...

# Robot objects



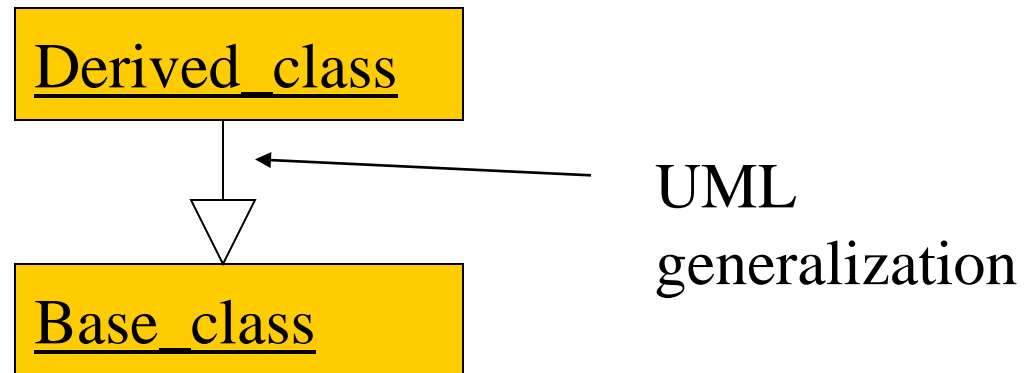
# Relationships between objects/classes

- ⌘ **Association**: objects communicate with each other → flight controller **controls** engine
- ⌘ **Aggregation**: a complex object is made of several smaller objects → multimedia: A/V, Robot object **contains** gripper (object)
- ⌘ **Composition**: Strong aggregation in which owner does not allow access to its components: Engine **has** a piston, sensor **has** A/D
- ⌘ **Generalization**: define one class in terms of another. → is-a-kind-of relationship, e.g. position sensor **is a kind of** sensor

# Class derivation

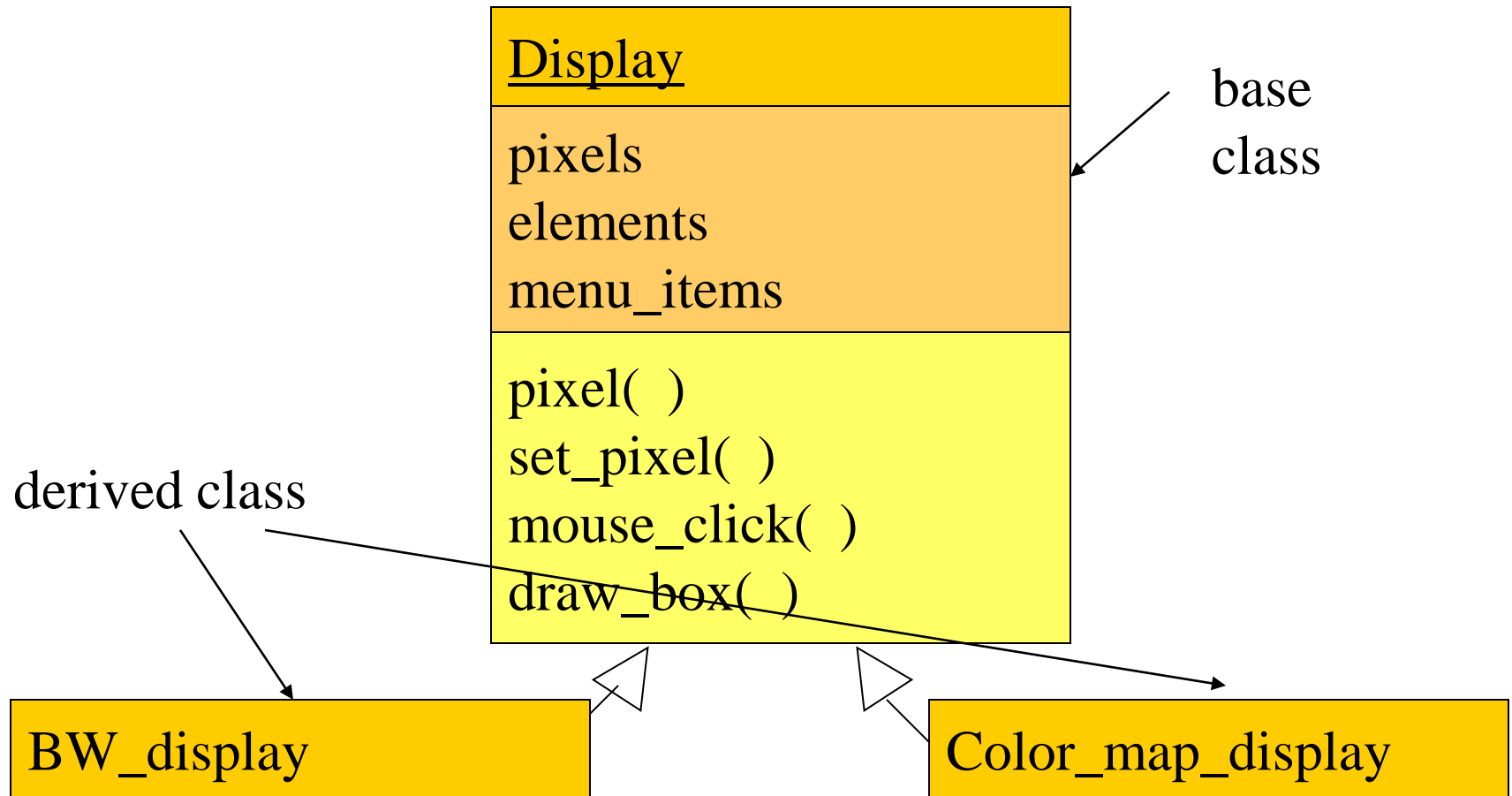
⌘ May want to define one class in terms of another.

☑ Derived class **inherits** attributes, operations of base class, e.g., robot on a track

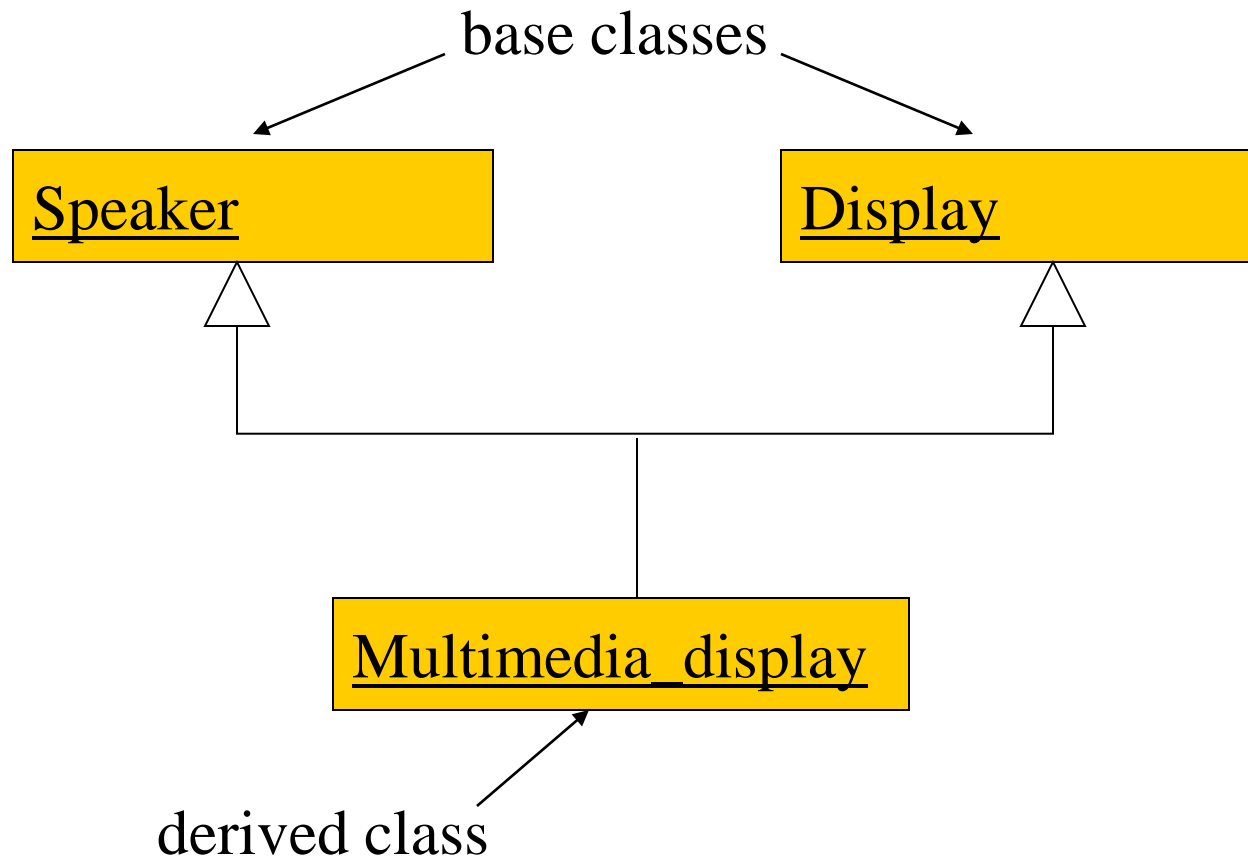


Taken/modified from "Computers as Components, W. Wolf"

# Class derivation example



# Multiple inheritance



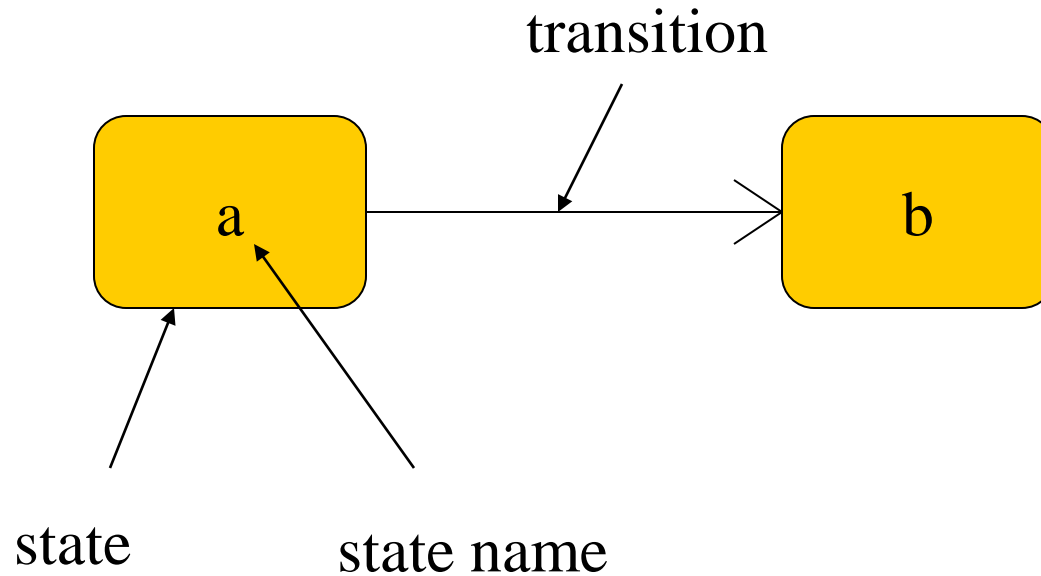
Taken/modified from "Computers  
as Components, W. Wolf"

# Behavioral description



- ⌘ State machines: One way to describe behavior
- ⌘ State machines work based on triggering of events

# State machines



Taken/modified from "Computers as Components, W. Wolf"

# Event-driven state machines



⌘ Behavioral descriptions are written as event-driven state machines.

☑ Machine changes state when receiving an input.

⌘ An event may come from inside or outside of the system.

# Types of events



⌘ **Signal**: asynchronous event.

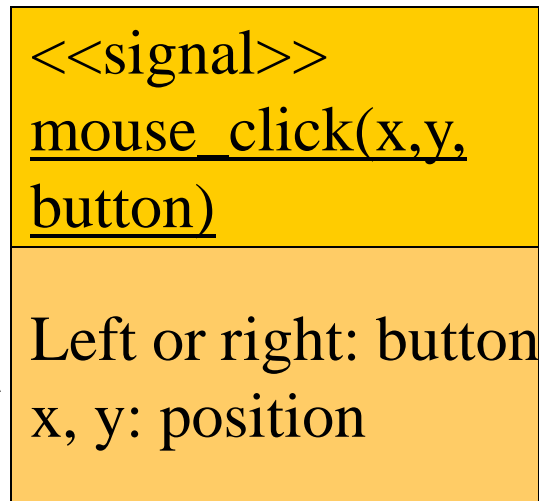
⌘ **Call**: synchronized communication.

⌘ **Timer**: activated by time.

# Signal event:

Asynchronous occurrence of an event

Signal event is defined in UML by an object that is labeled as a signal



name

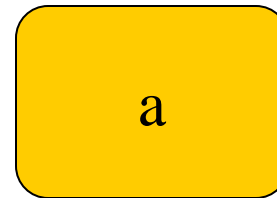
<<signal>>

mouse\_click(x,y,button)

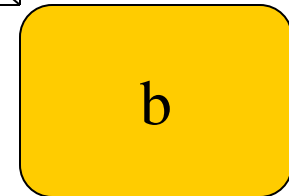
Left or right: button  
x, y: position

Declaration of  
Signal event

parameters

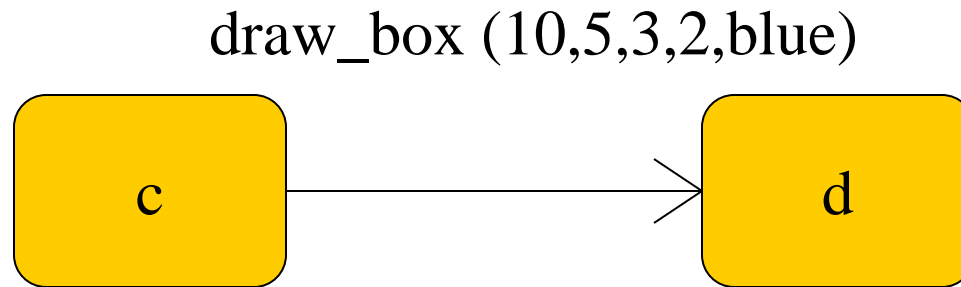


mouse\_click(x,y,button)



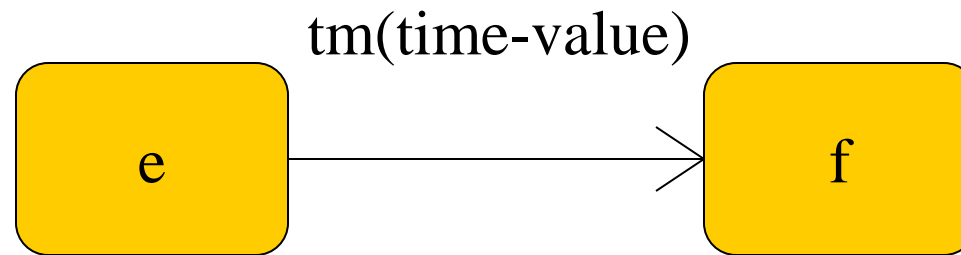
**Event description:** The occurrence of a signal is shown by mouse\_click( )

# Call event



Taken/modified from "Computers  
as Components, W. Wolf"

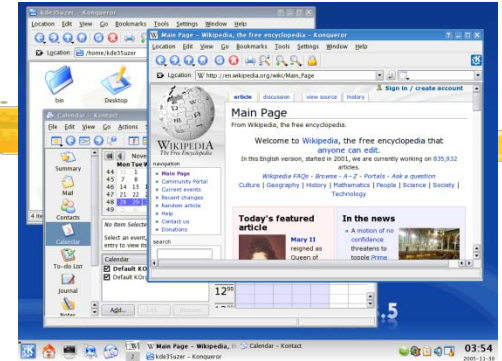
# Timer event



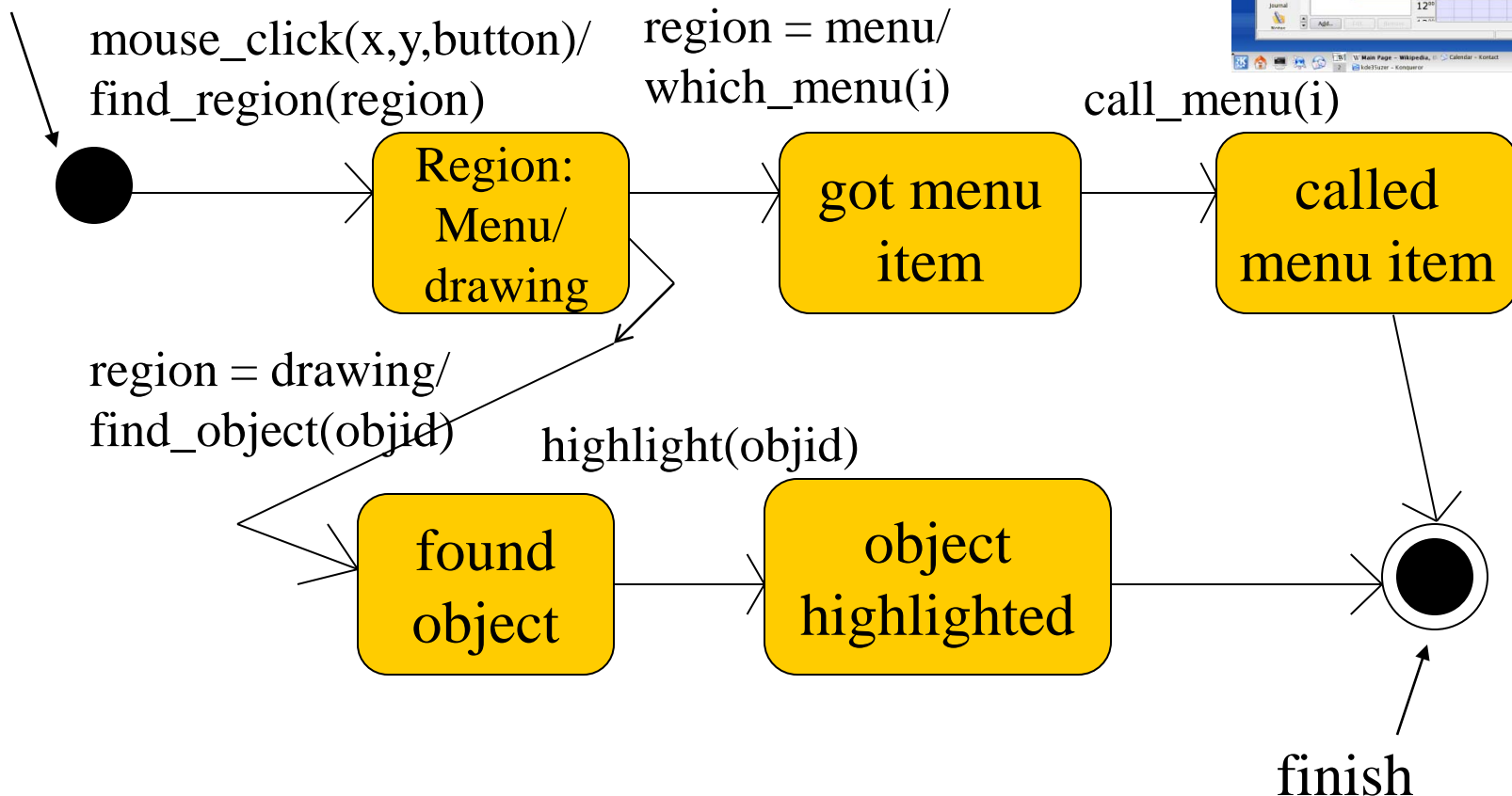
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# Example state machine:

Display with menu bars



start



Taken/modified from "Computers as Components, W. Wolf"

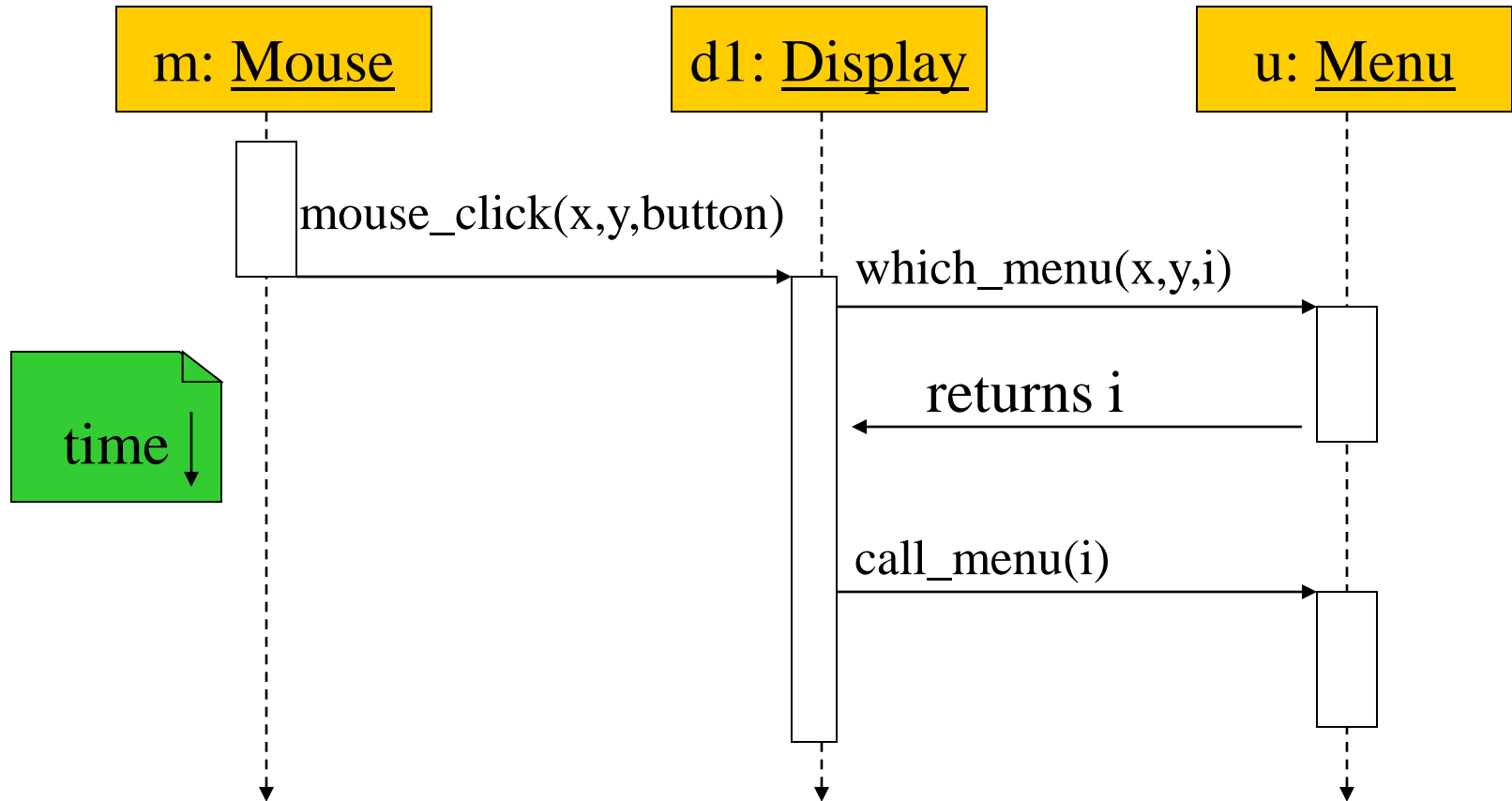
# Sequence diagram



- ⌘ Shows sequence of operations over time.
- ⌘ Relates behaviors of multiple objects.

# Sequence diagram example:

*Mouse click on the menu region*



Mouse, Display, and Menu are objects

# Summary



- ⌘ Object-oriented design (or object-based design) helps us organize a design.
- ⌘ UML is a transportable system design language.
  - ☑ Provides structural and behavioral description primitives.